

Some comments on the Born approximation

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Born Scattering Theory

$$\delta G(\mathbf{r}, \mathbf{s}) \approx \omega^2 \int G(\mathbf{x}, \mathbf{r}) \delta V(\mathbf{x}) G(\mathbf{x}, \mathbf{s}) d\mathbf{x}$$

(just symbolic)

- provides Fréchet differential kernel $dG(\mathbf{r}, \mathbf{s}) = \omega^2 \int G(\mathbf{x}, \mathbf{r}) dV(\mathbf{x}) G(\mathbf{x}, \mathbf{s}) d\mathbf{x}$
 - Green function can be FD
 - basis for most inverse methods (Tarantola, Pratt, Burridge *et al.*)
- allows modelling of scattered waves
 - Green function normally approximated by ray theory

Born Scattering Theory

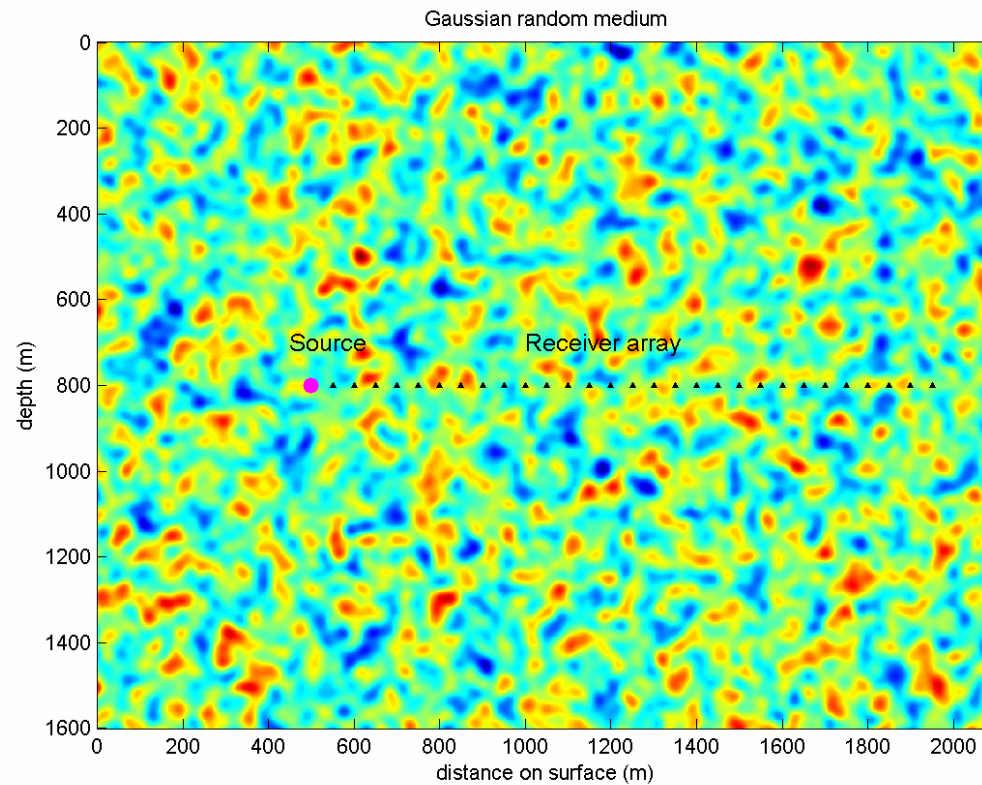
$$\delta G(\mathbf{r}, \mathbf{s}) \approx \omega^2 \int A(\mathbf{x}, \mathbf{r}) \delta V(\mathbf{x}) A(\mathbf{x}, \mathbf{s}) e^{i\omega(T(\mathbf{x}, \mathbf{r}) + T(\mathbf{x}, \mathbf{s}))} d\mathbf{x}$$

- cost in frequency domain $< N_x N_y N_z N_\omega$

$$\delta G(\mathbf{r}, \mathbf{s}) \approx -\frac{d^2}{dt^2} \int A(\mathbf{x}, \mathbf{r}) \delta V(\mathbf{x}) A(\mathbf{x}, \mathbf{s}) \delta(t - T(\mathbf{x}, \mathbf{r}) - T(\mathbf{x}, \mathbf{s})) d\mathbf{x}$$

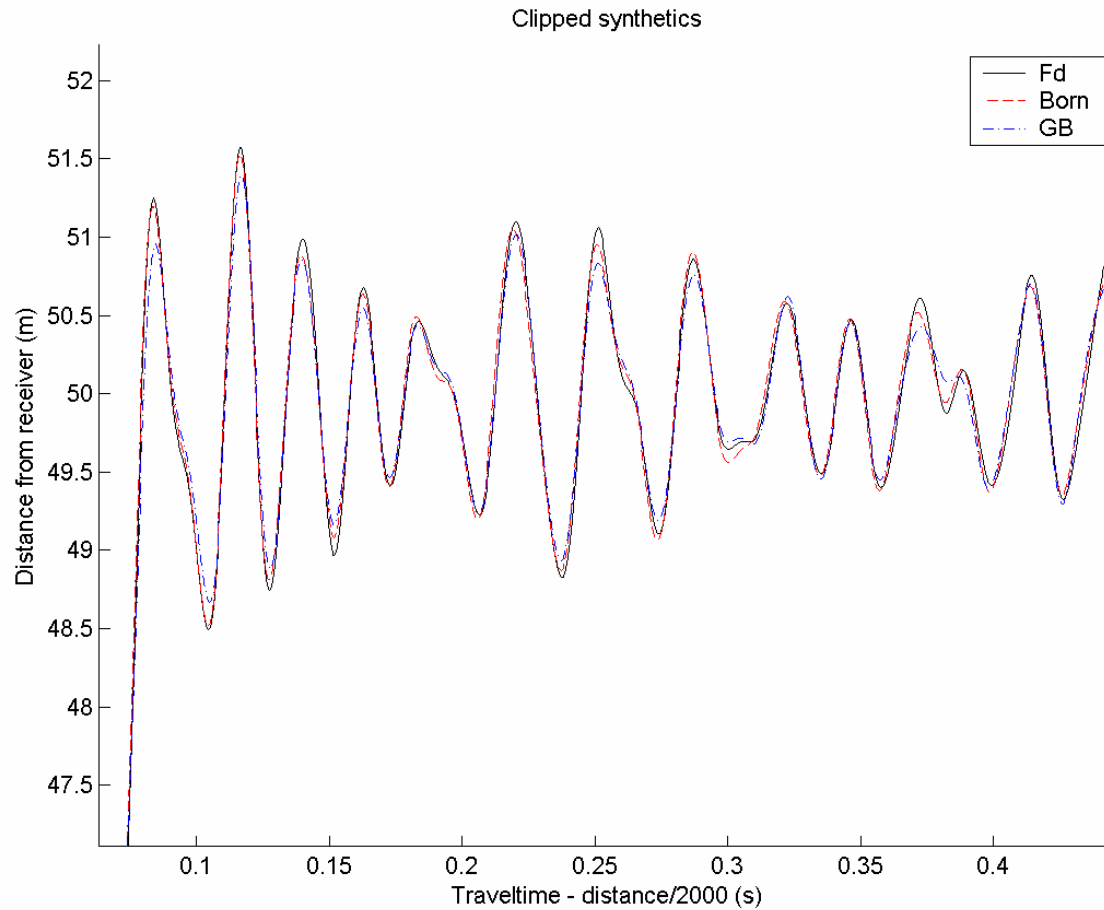
- cost in time domain $< N_x N_y N_z$
- so in 3D, time domain modelling is attractive

Model and Acquisition Geometry



(courtesy of E. Hopkins and H. Keers, SCR)

Traces at $x = 50\text{m}$, 2.5%



(courtesy of E. Hopkins and H. Keers, SCR)

Outline

- standard (**perturbation**) acoustic Born scattering
 - scattering by model perturbations
 - travel-time perturbations/Fréchet differential kernel
- generalized (**error**) acoustic Born scattering
 - approximate Green function, e.g. ray theory
 - scattering by errors in wave equation
- comparison with 1D inverse methods
 - inverse method for **parameter gradients**

Acoustic Born Scattering

- equation of motion

$$-\nabla \underline{P} = -\omega^2 \rho \underline{\mathbf{u}} - \mathbf{I} \delta(\mathbf{x} - \mathbf{s})$$

press grad density x acc force

- constitutive equation

$$\nabla \cdot \underline{\mathbf{u}} = -k \underline{P}$$

dilatation comp x press

- model perturbation B in model A

$$\rho = \rho^A + \rho^B$$

$$k = k^A + k^B$$

Acoustic Born Scattering

- solution is known in part A of model;
part B is perturbation
- perturbed equation of motion

$$-\nabla \underline{P}^A = -\omega^2 \rho \underline{\mathbf{u}}^A - \mathbf{I} \delta(\mathbf{x}-\mathbf{s}) + \omega^2 \rho^B \underline{\mathbf{u}}^A$$

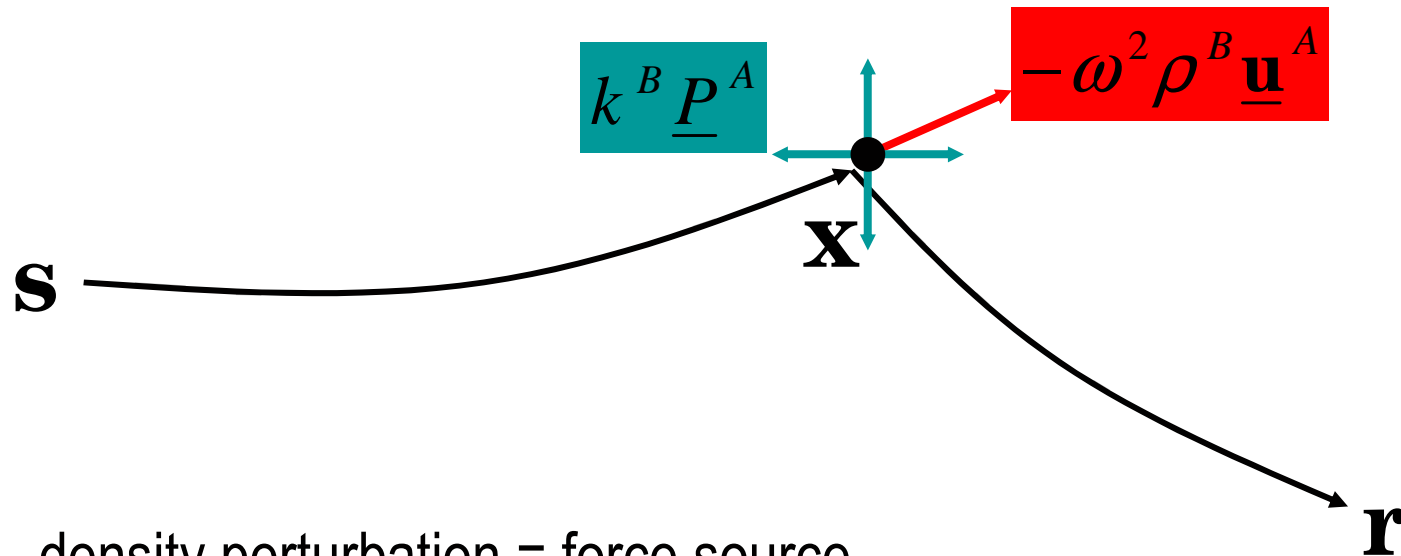
“force source”

- perturbed constitutive equation

$$\nabla \cdot \underline{\mathbf{u}}^A = -k \underline{P}^A + k^B \underline{P}^A$$

“press. source”

Point Scatterer



density perturbation = force source

compressibility perturbation = pressure source

Acoustic Born Scattering Integral

- general source using Green (point source) function

$$\underline{\mathbf{u}}(\omega, \mathbf{r}, \mathbf{s}) = \int_V \left(\begin{array}{l} \underline{\mathbf{u}}^T(\omega, \mathbf{x}, \mathbf{r}) \mathbf{f}_S(\omega, \mathbf{x}) \\ + \underline{P}^T(\omega, \mathbf{x}, \mathbf{r}) k_S P_S(\omega, \mathbf{x}) \end{array} \right) dV$$

volume integral of sources

- scattering source

$$\underline{\mathbf{u}}^B(\omega, \mathbf{r}, \mathbf{s}) = \int_V \left(\begin{array}{l} \underline{\mathbf{u}}^T(\omega, \mathbf{x}, \mathbf{r}) \omega^2 \rho^B(\mathbf{x}) \underline{\mathbf{u}}^A(\omega, \mathbf{x}, \mathbf{s}) \\ + \underline{P}^T(\omega, \mathbf{x}, \mathbf{r}) k^B(\mathbf{x}) \underline{P}^A(\omega, \mathbf{x}, \mathbf{s}) \end{array} \right) dV$$

volume integral of scattering sources

- note $\underline{\mathbf{u}} = \underline{\mathbf{u}}^A + \underline{\mathbf{u}}^B$ in integral

Acoustic Born Scattering Approximation

- approximate full Green function by Green function in reference medium

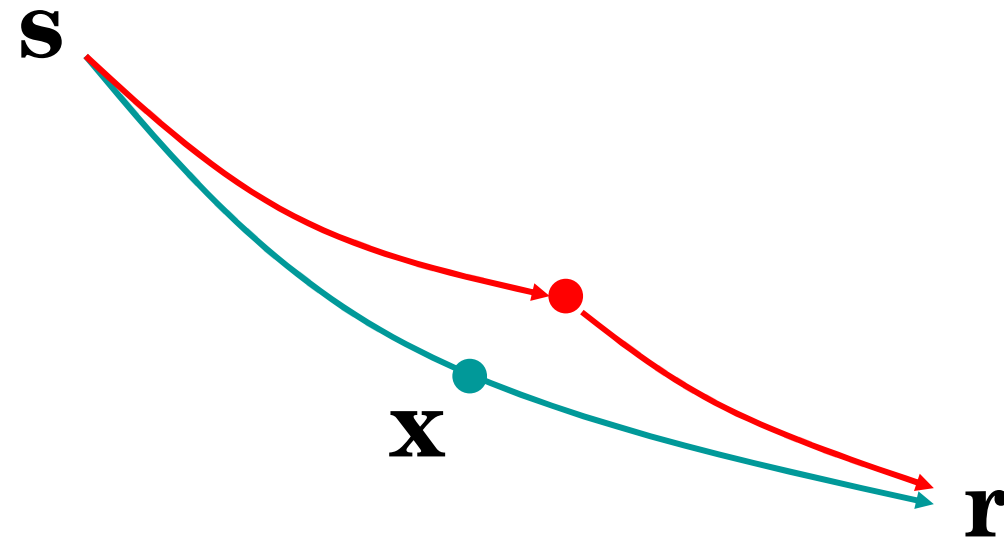
$$\underline{\mathbf{u}}^B(\omega, \mathbf{r}, \mathbf{s}) \approx \int_V \left(\begin{array}{l} \underline{\mathbf{u}}^{A^T}(\omega, \mathbf{x}, \mathbf{r}) \omega^2 \rho^B(\mathbf{x}) \underline{\mathbf{u}}^A(\omega, \mathbf{x}, \mathbf{s}) \\ + \underline{P}^{A^T}(\omega, \mathbf{x}, \mathbf{r}) k^B(\mathbf{x}) \underline{P}^A(\omega, \mathbf{x}, \mathbf{s}) \end{array} \right) dV$$

volume integral of scattering sources
with Green function in reference medium

Pros and Cons

- excellent if perturbations are small and isolated
- but
 - assumes Green function known exactly
 - assumes perturbation has little effect on Green function
- what if Green function is approximate?
- in general, how do we choose choose perturbation?
- what if perturbations are extensive -
how are ray results perturbed?

The Ray Theory Approximation in the Born Volume



$$G(\omega, \mathbf{x}, \mathbf{s}) = A(\mathbf{x}, \mathbf{s}) e^{i\omega T(\mathbf{x}, \mathbf{s})}$$

Ray Theory - an Approximate Green function

$$\begin{matrix} & \text{transmission} & & \text{dyadic} \\ \begin{pmatrix} -i\omega \underline{\mathbf{u}}^A \\ -\underline{P}^A \end{pmatrix} & = -\frac{i\omega}{2\pi} e^{i\omega T} \mathcal{T}(\mathbf{x}, \mathbf{s}) & \begin{pmatrix} \mathbf{g} \\ -(Z/2)^{1/2} \end{pmatrix}(\mathbf{x}) & \mathbf{g}^T(\mathbf{s}) \end{matrix}$$

$$Z = \rho \alpha \quad \text{impedance}$$

$$\mathbf{g} = (2Z)^{-1/2} \hat{\mathbf{g}} \quad \text{energy-normalized polarization}$$

$$\mathcal{T}(\mathbf{x}, \mathbf{s}) = \mathcal{S}^{-1/2}(\mathbf{x}, \mathbf{s}) e^{-i\pi\sigma(\mathbf{x}, \mathbf{s})/2} \quad \text{transmission function}$$

$$\mathcal{S}(\mathbf{x}, \mathbf{s}) = \left| \frac{\partial \mathbf{x}}{\partial q_1} \times \frac{\partial \mathbf{x}}{\partial q_2} \right| \bigg/ \left| \frac{\partial \mathbf{p}_s}{\partial q_1} \times \frac{\partial \mathbf{p}_s}{\partial q_2} \right| = [c(\mathbf{s}) \mathcal{R}(\mathbf{x}, \mathbf{s})]^2 \quad \text{spreading function}$$

Acoustic Born Scattering Approximation

frequency domain

$$\underline{\mathbf{u}}^B(\omega, \mathbf{r}, \mathbf{s}) \approx \frac{\omega^2}{4\pi^2} \int_V \mathbf{K}^B(\mathbf{x}, \mathbf{r}, \mathbf{s}) e^{i\omega T(\mathbf{x}, \mathbf{r}, \mathbf{s})} dV$$

$$\mathbf{K}^B(\mathbf{x}, \mathbf{r}, \mathbf{s}) = -\mathbf{g}(\mathbf{r}) \mathcal{T}(\mathbf{x}, \mathbf{r}) \Gamma^B(\mathbf{x}, \mathbf{r}, \mathbf{s}) \mathcal{T}(\mathbf{x}, \mathbf{s}) \mathbf{g}^T(\mathbf{s})$$

$$\Gamma^B(\mathbf{x}, \mathbf{r}, \mathbf{s}) = \mathbf{g}^T(\mathbf{x}, \mathbf{r}) \rho^B(\mathbf{x}) \mathbf{g}(\mathbf{x}, \mathbf{s}) - \frac{1}{2} Z(\mathbf{x}) k^B(\mathbf{x})$$

scattering scalar amplitude (independent of frequency)

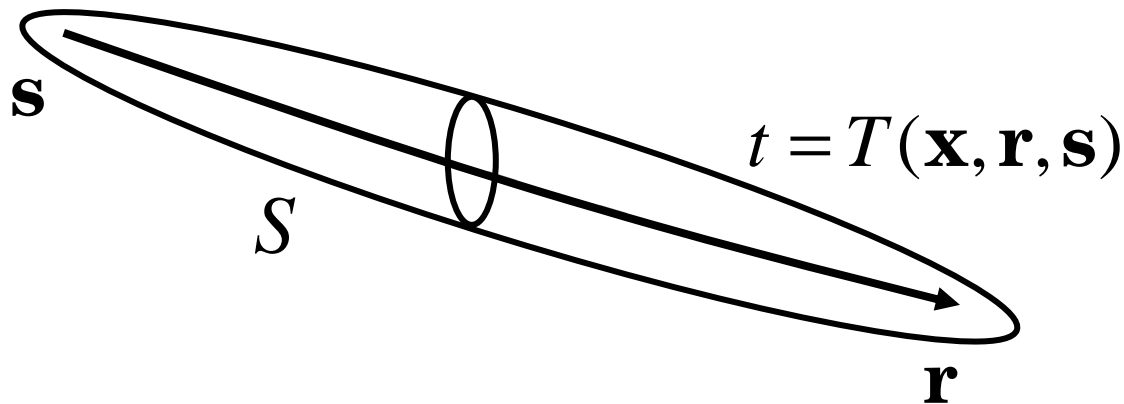
$$T(\mathbf{x}, \mathbf{r}, \mathbf{s}) = T(\mathbf{x}, \mathbf{r}) + T(\mathbf{x}, \mathbf{s})$$

total scattered travel time

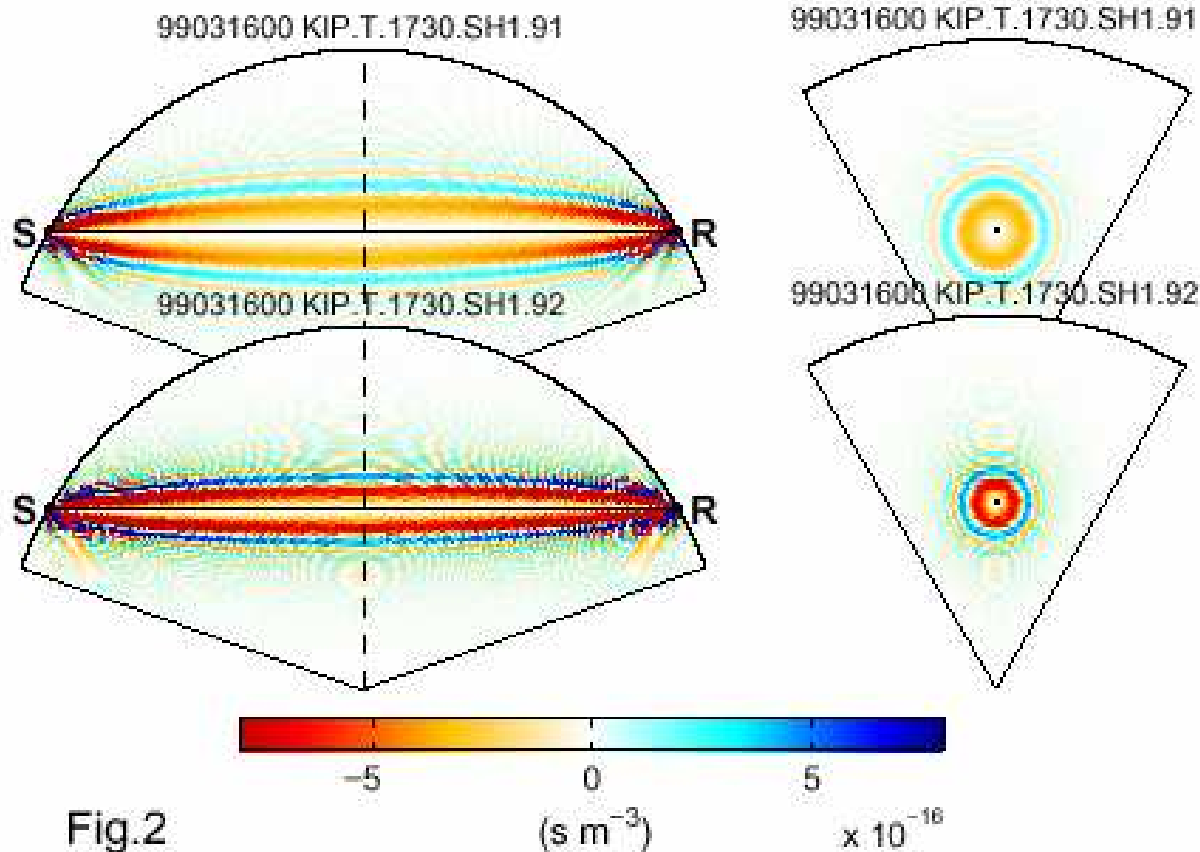
Acoustic Born Scattering Approximation

time domain

$$\begin{aligned}\underline{\mathbf{u}}^B(t, \mathbf{r}, \mathbf{s}) &\approx -\frac{1}{4\pi^2} \frac{d^2}{dt^2} \int_V \mathbf{K}^B(\mathbf{x}, \mathbf{r}, \mathbf{s}) \delta(t - T(\mathbf{x}, \mathbf{r}, \mathbf{s})) dV \\ &= -\frac{1}{4\pi^2} \frac{d^2}{dt^2} \int_S \frac{\mathbf{K}^B(\mathbf{x}, \mathbf{r}, \mathbf{s})}{|\nabla T(\mathbf{x}, \mathbf{r}, \mathbf{s})|} dS\end{aligned}$$



Born Kernel for Travel Time



L. Zhao, T.H. Jordan and C.H. Chapman, 2000.

Three-dimensional Fréchet differential kernels for seismic delay times,
Geophys. J. Intl., **141**, 558-576.

CHC 14/08/06

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Point Perturbation **On** and **Off** Ray

$$\mathbf{u}^B(t, \mathbf{r}, \mathbf{s}) = -\ddot{\delta}(t - T(\mathbf{r}, \mathbf{s}) - \delta T) \mathbf{K}^B(\mathbf{x}, \mathbf{r}, \mathbf{s}) \Delta V$$

- Born scattering is second derivative of incident pulse
- on-ray scattering, pulse only distorted, not delayed
- travelttime perturbation is due to perturbations *off* the ray (within Fresnel zone), integrating laterally to give first derivative of incident pulse

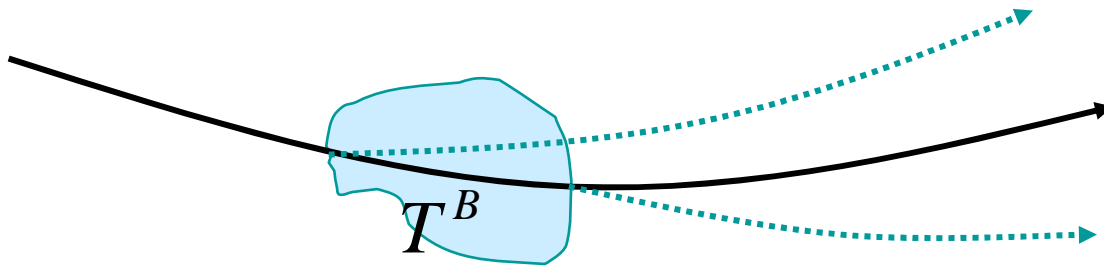
Born Scattering Theory for Modelling

$$\delta G(\mathbf{r}, \mathbf{s}) = -\frac{d^2}{dt^2} \int A(\mathbf{x}, \mathbf{r}) \delta V(\mathbf{x}) A(\mathbf{x}, \mathbf{s}) \delta(t - T(\mathbf{x}, \mathbf{r}) - T(\mathbf{x}, \mathbf{s})) d\mathbf{x}$$

- efficient in time domain
- efficient for small isolated scatterers
- intuitively not physical for extended scatterers
 - scattering should be from gradients not perturbations
- only models travel time correction as $e^{i\omega\delta T} \approx 1 + i\omega\delta T$
for extended scatterers

Born Scattering Dichotomy

- for an extended perturbation, the Born approximation must correct travel times, plus model scattering from edges of perturbation
- it gives a perturbation $\underline{\mathbf{u}}^B(\omega, \mathbf{r}, \mathbf{s}) \approx -i\omega \underline{\mathbf{u}}^A(\omega, \mathbf{r}, \mathbf{s}) T^B$ which at high frequencies is a *very poor* approximation
- if the perturbation is halved, $k^A + k^B/2 \Rightarrow k^A$, $k^B/2 \Rightarrow k^B$ the travel-time error is reduced, but the scattered signal from the edges is also reduced!



Generalized Born Scattering

- recall wave equation with perturbation

$$-\nabla \underline{P}^A = -\omega^2 \rho \underline{\mathbf{u}}^A - \mathbf{I} \delta(\mathbf{x} - \mathbf{s}) + \omega^2 \rho^B \underline{\mathbf{u}}^A$$

- suppose \underline{P}^A and $\underline{\mathbf{u}}^A$ are *not* exact solutions in model A
- error in equation of motion

$$\underline{\mathbf{F}}^A = \omega^2 \rho^A \underline{\mathbf{u}}^A - \nabla \underline{P}^A + \mathbf{I} \delta(\mathbf{x} - \mathbf{s}) \neq \underline{\mathbf{0}}$$

- similarly in constitutive equation error is

$$\underline{\Theta}^A = \nabla \cdot \underline{\mathbf{u}}^A + k^A \underline{P}^A \neq \underline{\mathbf{0}}$$

- note these are **definitions** of errors not differential equations

Generalized Born Scattering

- modified equation of motion and constitutive equation

$$-\nabla \underline{P}^A = -\omega^2 \rho \underline{u}^A - \mathbf{I} \delta(\mathbf{x} - \mathbf{s}) + \underline{\mathcal{E}}^N$$

error + perturbation

$$\nabla \cdot \underline{u}^A = -k \underline{P}^A + \underline{\mathcal{E}}^H \quad \text{similarly}$$

- where

$$\underline{\mathcal{E}}^N = \underline{\mathbf{F}}^A + \omega^2 \rho^B \underline{u}^A$$

$$\underline{\mathcal{E}}^H = \underline{\Theta}^A + k^B \underline{P}^A$$

errors perturbations

Generalized Born Scattering

- standard Born scattering (perturbations are sources)

$$\underline{\mathbf{u}}^B(\omega, \mathbf{r}, \mathbf{s}) = \int_V \left(\begin{array}{l} \underline{\mathbf{u}}^T(\omega, \mathbf{x}, \mathbf{r}) \omega^2 \rho^B(\mathbf{x}) \underline{\mathbf{u}}^A(\omega, \mathbf{x}, \mathbf{s}) \\ + \underline{P}^T(\omega, \mathbf{x}, \mathbf{r}) k^B(\mathbf{x}) \underline{P}^A(\omega, \mathbf{x}, \mathbf{s}) \end{array} \right) dV$$

- generalized Born scattering (errors+perturbations are sources)

$$\underline{\mathbf{u}}^B(\omega, \mathbf{r}, \mathbf{s}) = \int_V \left(\begin{array}{l} \underline{\mathbf{u}}^T(\omega, \mathbf{x}, \mathbf{r}) \underline{\mathcal{E}}^N(\omega, \mathbf{x}, \mathbf{s}) \\ + \underline{P}^T(\omega, \mathbf{x}, \mathbf{r}) \underline{\mathcal{E}}^H(\omega, \mathbf{x}, \mathbf{s}) \end{array} \right) dV$$

Generalized Born Approximation

- ray approximation

$$\begin{pmatrix} -i\omega \underline{\mathbf{u}}^A \\ -\underline{P}^A \end{pmatrix} = -\frac{i\omega}{2\pi} e^{i\omega T} \begin{pmatrix} \underline{\mathbf{v}}^{(0)} \\ -\underline{P}^{(0)} \end{pmatrix} = -\frac{i\omega}{2\pi} e^{i\omega T} \mathcal{F}(\mathbf{x}, \mathbf{s}) \begin{pmatrix} \mathbf{g} \\ -(Z/2)^{1/2} \end{pmatrix}(\mathbf{x}) \mathbf{g}^T(\mathbf{s})$$

- error terms

$$\underline{\mathbf{F}}^A = \frac{i\omega}{2\pi} e^{i\omega T} \nabla \underline{P}^{(0)}$$

$$\underline{\Theta}^A = \frac{1}{2\pi} e^{i\omega T} \nabla \cdot \underline{\mathbf{v}}^{(0)}$$

Generalized Born Approximation

time domain

$$\underline{\mathbf{u}}^B(t, \mathbf{r}, \mathbf{s}) \approx -\frac{1}{4\pi^2} \frac{d^2}{dt^2} \int_S \frac{\mathbf{K}^B(\mathbf{x}, \mathbf{r}, \mathbf{s})}{|\nabla T(\mathbf{x}, \mathbf{r}, \mathbf{s})|} dS \quad \begin{array}{l} \text{perturbation} \\ \text{scattering} \end{array}$$
$$+ \frac{1}{4\pi^2} \frac{d}{dt} \int_S \frac{\mathbf{K}^E(\mathbf{x}, \mathbf{r}, \mathbf{s})}{|\nabla T(\mathbf{x}, \mathbf{r}, \mathbf{s})|} dS \quad \begin{array}{l} \text{error} \\ \text{scattering} \end{array}$$

Generalized Born Approximation

- acoustic scattering kernel

$$\begin{aligned}\mathbf{K}^E(\mathbf{x}, \mathbf{r}, \mathbf{s}) &= -\underline{\mathbf{v}}_R^{(0)\text{T}} \nabla \underline{P}_S^{(0)} + \underline{P}_R^{(0)\text{T}} \nabla \cdot \underline{\mathbf{v}}_S^{(0)} \\ &= -\frac{1}{2} \left[\underline{\mathbf{v}}_R^{(0)\text{T}} \nabla \underline{P}_S^{(0)} - \underline{P}_R^{(0)\text{T}} \nabla \cdot \underline{\mathbf{v}}_S^{(0)} + \left(\nabla \underline{P}_R^{(0)} \right)^{\text{T}} \underline{\mathbf{v}}_S^{(0)} - \left(\nabla \cdot \underline{\mathbf{v}}_R^{(0)} \right)^{\text{T}} \underline{P}_S^{(0)} \right] \\ &\approx -\mathbf{g}(\mathbf{r}) \mathcal{T}_R \Gamma^E \mathcal{T}_S \mathbf{g}^{\text{T}}(\mathbf{s})\end{aligned}$$

(ignoring derivatives of source and receiver directivity)

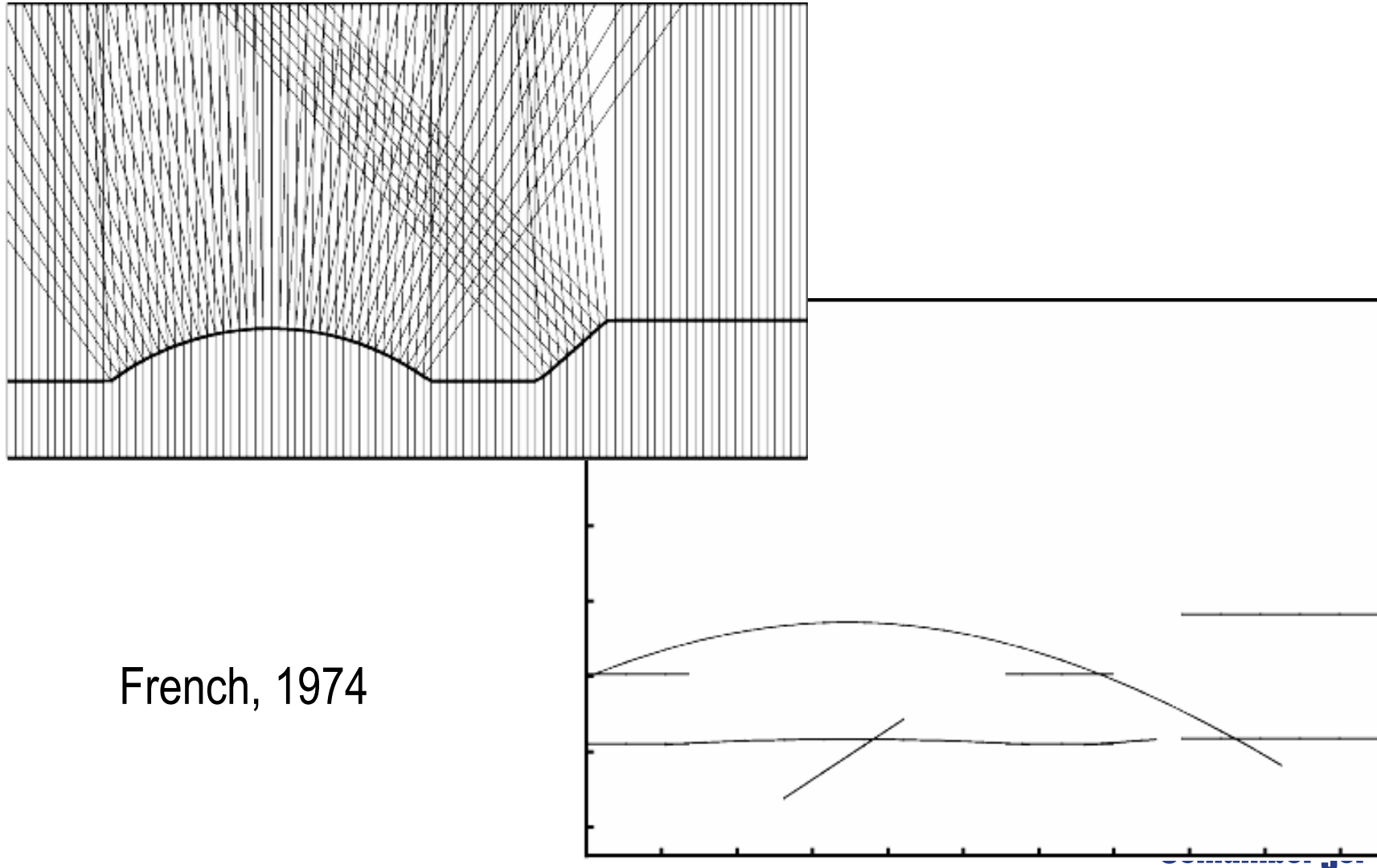
Generalized Born Approximation

- scalar ray acoustic scattering kernel

$$\begin{aligned}\Gamma^E(\mathbf{x}, \mathbf{r}, \mathbf{s}) &= \frac{1}{4} \left(\frac{\nabla Z}{Z} - \nabla \right) \cdot (\hat{\mathbf{g}}_R + \hat{\mathbf{g}}_S) - \frac{1}{4} \left(\nabla \ln \frac{\mathcal{T}_R}{\mathcal{T}_S} \right) \cdot (\hat{\mathbf{g}}_R - \hat{\mathbf{g}}_S) \\ &= \frac{1}{4} (\hat{\mathbf{g}}_R + \hat{\mathbf{g}}_S) \cdot \nabla \ln(Z \mathcal{T}_R \mathcal{T}_S)\end{aligned}$$

using energy conservation $\nabla \cdot (\mathcal{T}^2 \mathbf{g}) = 0$

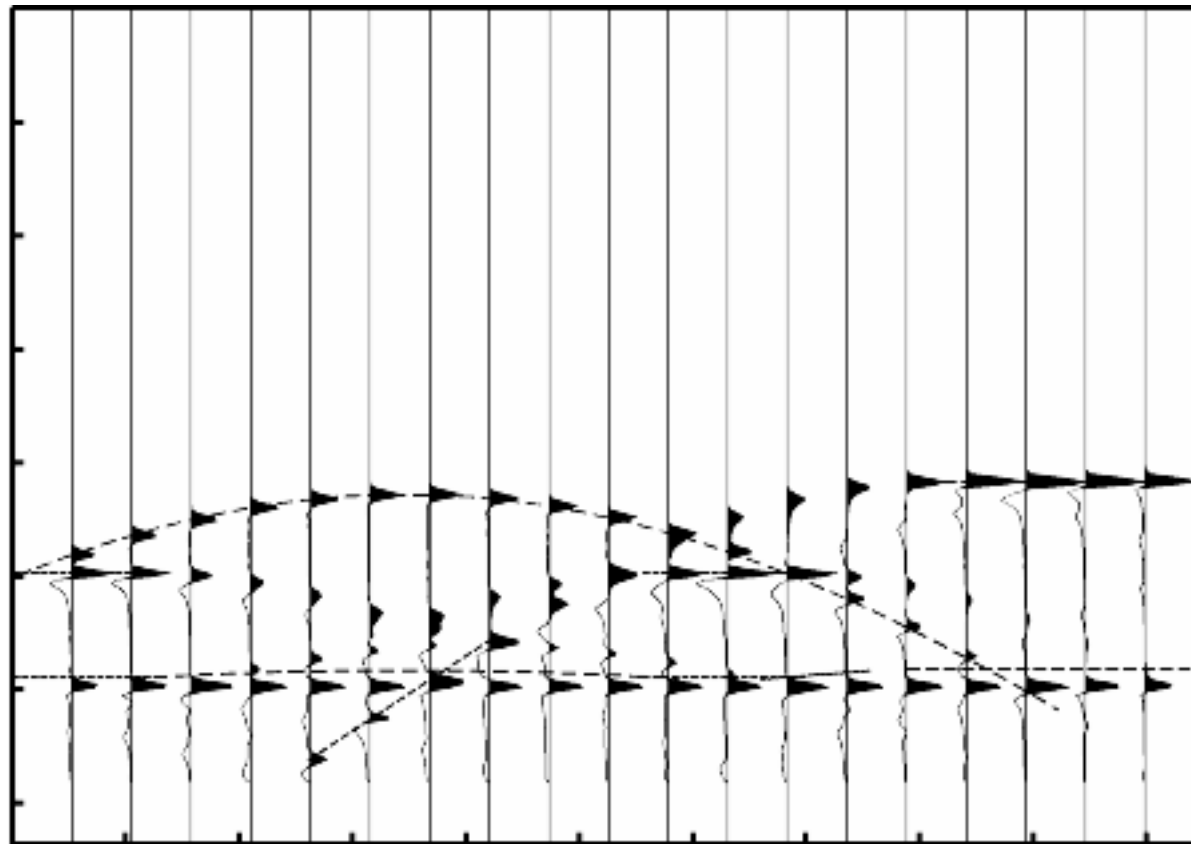
'2D' Profile in French Model



Born Perturbation in French Model

– volume scattering from model perturbation

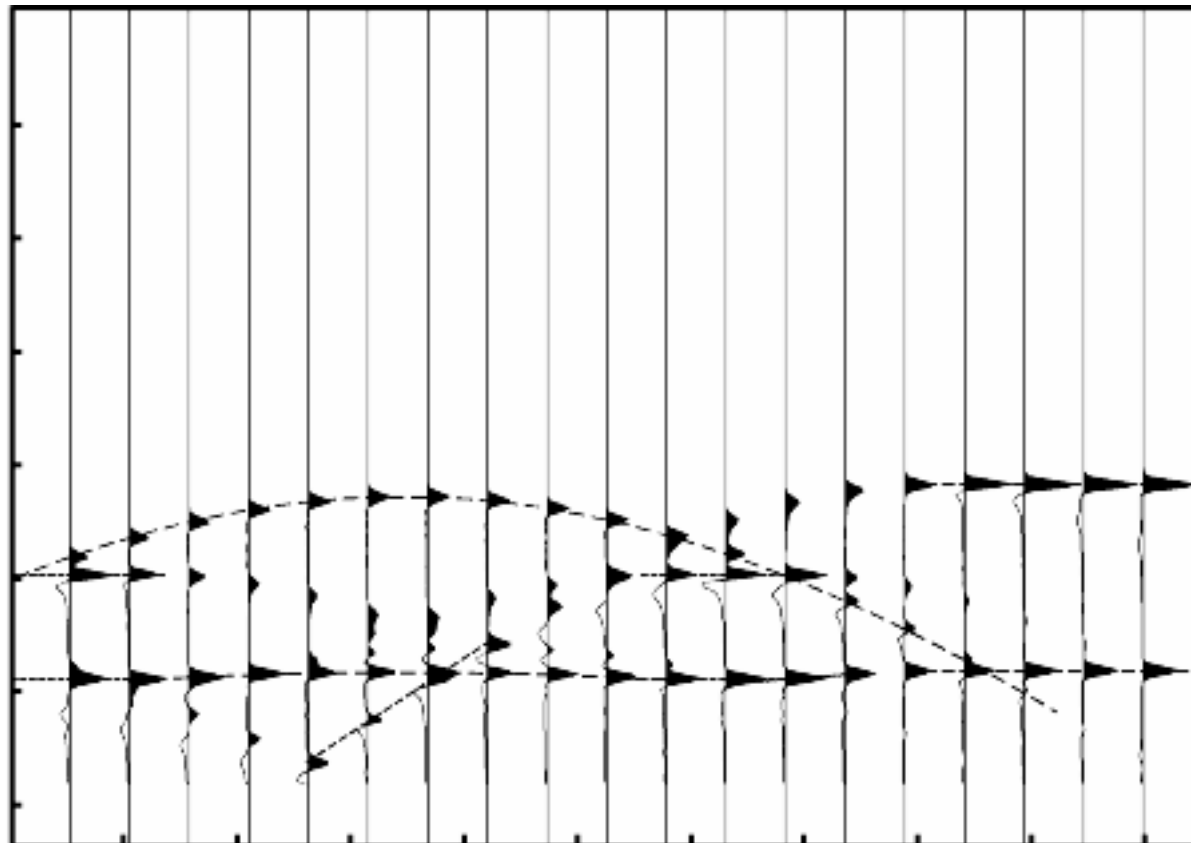
$$\mathbf{u} = \frac{1}{4\pi^2} \frac{d^2}{dt^2} \int_V \text{Re} [\Delta(t - \tilde{T}) \mathbf{K}] dV \quad \Gamma^B = \rho^B \mathbf{g}_R^T \mathbf{g}_S - k^B Z / 2$$



Born Error in French Model

– volume scattering from ray theory errors

$$\mathbf{u} = -\frac{1}{4\pi^2} \frac{d}{dt} \int_V \operatorname{Re} [\Delta(t - \tilde{T}) \mathbf{K}] dV \quad \Gamma^E = \frac{1}{4} (\hat{\mathbf{g}}_R + \hat{\mathbf{g}}_S) \cdot \nabla \ln(Z \mathcal{T}_R \mathcal{T}_S)$$



Elastic Generalized Born

- just as acoustic generalized Born except

$$\Gamma^B(\mathbf{x}, \mathbf{r}, \mathbf{s}) \text{ and } \Gamma^E(\mathbf{x}, \mathbf{r}, \mathbf{s})$$

are more complicated

Generalized Born Approximation

- references

- C.H. Chapman and R.T. Coates, 1994.
Generalized Born scattering in anisotropic media,
Wave Motion, **19**, 309-341.
- R.T.Coates and C.H.Chapman, 1991.
Generalized Born scattering of elastic waves in 3-D media,
Geophys.J.Int., **107**, 231-263.
- C.H.Chapman, 2004.
Fundamentals of Seismic Wave Propagation,
Cambridge University Press.

cf. Transformed Wave Equation in 1D Model

- to understand generalized Born
- to investigate the inverse problem

$$\frac{d\mathbf{w}}{dz} = i\omega \mathbf{A} \mathbf{w}$$

1D differential wave equation
in (ω, p, z) domain

$$\mathbf{w} = \begin{pmatrix} v_z \\ -P \end{pmatrix}$$

variables

$$\mathbf{A} \mathbf{W} = \mathbf{W} \mathbf{p}$$

eigen-equation (U/D separation)

$$\tau = \int^z \mathbf{p} d\zeta$$

vertical delay time

Bremmer Coupling Equations

$$\mathbf{w} = \mathbf{W} \exp(i\omega\tau) \mathbf{r} \quad \text{resolve into U/D components}$$

$$\mathbf{W} \exp(i\omega\tau) = \text{“rays”} \quad \mathbf{r} = \text{“ray amplitudes”}$$

$$\frac{d\mathbf{r}}{dz} = \exp(-i\omega\tau) \mathbf{C} \exp(i\omega\tau) \mathbf{r} \quad \text{coupling differential equation}$$

$$\mathbf{C} = -\mathbf{W}^{-1} \frac{d\mathbf{W}}{dz} \quad \text{coupling differential coefficients}$$

$$\mathbf{r}^{(n+1)} = \mathbf{r}^{(n)} + \int^z \exp(-i\omega\tau) \mathbf{C} \exp(i\omega\tau) \mathbf{r}^{(n)} d\zeta \quad \text{iterative coupling}$$

“Born error series”

$$\mathbf{C} \rightarrow \Gamma^E$$

Differential Coupling Coefficients

$$\mathbf{C} = -\mathbf{W}^{-1} \frac{d\mathbf{W}}{dz} = \begin{pmatrix} 0 & \gamma_A \\ \gamma_A & 0 \end{pmatrix}$$

$$\gamma_A = -\frac{1}{2} \frac{d}{dz} \ln \left(\frac{\rho}{q_\alpha} \right)$$

- 1D Bremmer iterative solution
 - H. Bremmer, 1949
Terrestrial Radio Waves
Elsevier Publishing Company, p. 159
 - J.G.J. Scholte, 1962
Oblique propagation of waves in inhomogeneous media
Geophys. J.R. astr. Soc., **7**, 244-261

1D Inverse Problem

- classic solutions
 - Gel'fand & Levitan (1951), Marchenko (1955), Gopinath-Sondhi (1971), Blagoveschenskiy (1978), ...
(R. Burridge, 1980. The Gelfand-Levitan, the Marchenko, and the Gopinath-Sondhi integral equation of inverse scattering theory, regarded in the context of inverse-reponse problems, *Wave Motion*, **2**, 305-323)
- K. Bube and R. Burridge, 1982. The one-dimensional inverse problem of reflection seismology, *SIAM Rev.*, **25**, 497-559.
 - downward propagate wave variables \mathbf{w}
 - causal point gives reflected wave
 - ratio of components of wave variables gives $v_z/P = q_\alpha/\rho$
material properties

1D Inverse Problem – *Bailey's method*

- R.C. Bailey, 1970. *Some inverse problems in geophysics*, Ph.D. thesis, Cambridge University.
 - N.D. Bregman, C.H. Chapman and R.C. Bailey, 1985. A non-iterative procedure for inverting plane-wave reflection data at several angles of incidence using the Riccati Equation, *Geophys. Prosp.*, **33**, 185-200.
 - downward propagate reflectivity $R = r_1 / r_2$
 - causal point gives differential reflection coefficient γ_A
- ray continuation
 - downward propagate ray amplitudes \mathbf{r}
 - causal point gives differential reflection coefficient γ_A

Ricatti Reflectivity Equation

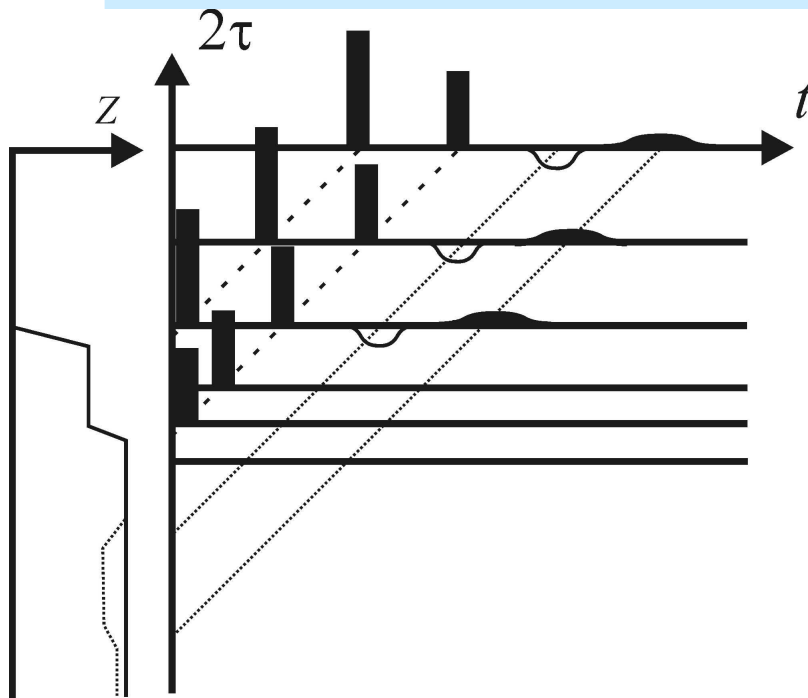
$$R(\omega, p, \tau) = \frac{r_1(\omega, p, \tau)}{r_2(\omega, p, \tau)} \equiv \text{reflectivity (up/down)}$$

$$r_1(t, p, 0) \equiv \text{data}$$

$$r_2(t, p, 0) \equiv \text{source}$$

$$\frac{1}{2} \frac{dR}{d\tau} = i\omega R + \gamma_A(1 - R^2) \quad \text{Ricatti equation}$$

$$\frac{1}{2} \frac{d}{d\tau} R(t, p, \tau) = -\frac{d}{dt} R(t, p, \tau) + \gamma_A(p, \tau)(\delta(t) - R(t, p, \tau) * R(t, p, \tau))$$



$$\gamma_A = -\frac{1}{2} \frac{\partial}{\partial \tau} \ln \left(\frac{\rho}{q_\alpha} \right) \equiv \text{diff. reflection coeff.}$$

$$R(0-, p, \tau) = 0 \quad \text{causality}$$

$$R^{(1)}(t, p, \tau) = \gamma_A(p, 2\tau - t)H(t) \quad \text{1st iteration}$$

$$r_1(t, p, 0) = r_2(t, p, 0) * \gamma_A(p, -t)H(t) \quad \text{convolution model}$$

$$\gamma_A(p, 2\tau) = R(0+, p, \tau) \quad \text{inverse solution}$$

Differential Coupling Coefficients

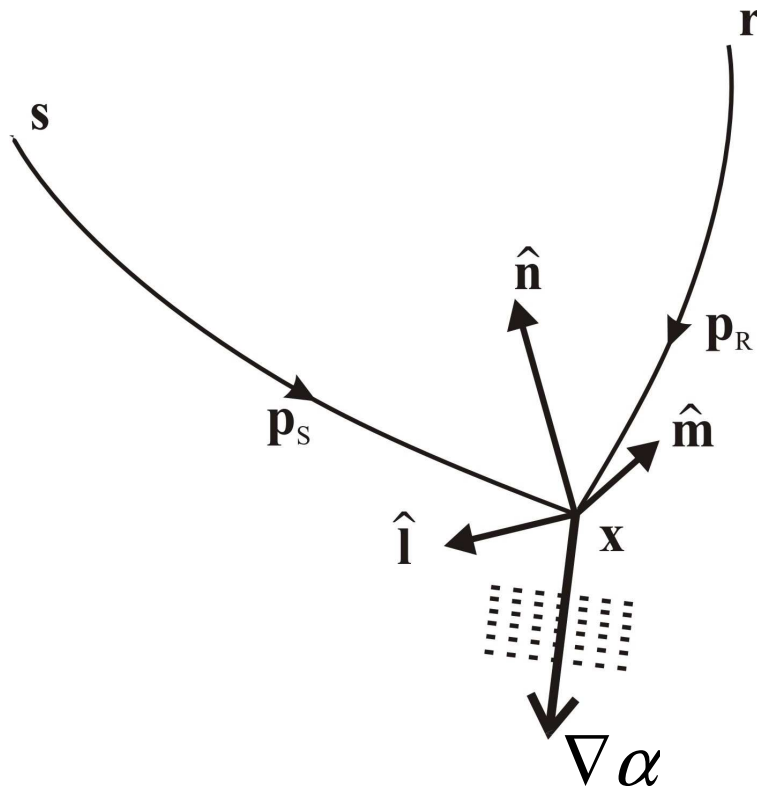
$$\mathbf{C} = -\mathbf{W}^{-1} \frac{d\mathbf{W}}{dz} = \begin{pmatrix} 0 & \gamma_A \\ \gamma_A & 0 \end{pmatrix}$$

$$\gamma_A = -\mathbf{w}_R^{\text{symplectic}} \mathbf{w}'_S = -V_R \frac{dP_S}{dz} - P_R \frac{dv_S}{dz} = -\frac{1}{2} \frac{d}{dz} \ln \left(\frac{\rho}{q_\alpha} \right)$$

cf. generalized Born approximate kernel

$$\mathbf{K}^E(\mathbf{x}, \mathbf{r}, \mathbf{s}) = -\underline{\mathbf{v}}_R^{(0)\text{T}} \nabla \underline{P}_S^{(0)} + \underline{P}_R^{(0)\text{T}} \nabla \cdot \underline{\mathbf{v}}_S^{(0)}$$

Generalized Born v. 1D Bremmer



at reflection point use
Snell coordinates

$$\hat{\mathbf{n}} = -\text{sgn}(\mathbf{p}_R + \mathbf{p}_S)$$

$$\hat{\mathbf{m}} = \text{sgn}(\hat{\mathbf{n}} \times \mathbf{p}_S)$$

$$\hat{\mathbf{l}} = \hat{\mathbf{m}} \times \hat{\mathbf{n}}$$

so

$$\hat{\mathbf{l}} \cdot (\mathbf{p}_R + \mathbf{p}_S) = 0$$

Generalized Born v. 1D Bremmer

$$\mathbf{K}^E(\mathbf{x}, \mathbf{r}, \mathbf{s}) = \underline{\mathbf{v}}_R^{(0)T} \frac{\partial \underline{\mathbf{t}}_{Sj}^{(0)}}{\partial x_j} - \underline{\mathbf{t}}_{Rj}^{(0)T} \frac{\partial \underline{\mathbf{v}}_S^{(0)}}{\partial x_j}$$

$$\approx -\mathbf{g}(\mathbf{r}) \mathcal{T}_R \Gamma^E \mathcal{T}_S \mathbf{g}^T(\mathbf{s}) \quad + \text{source/receiver} \\ \text{directivity derivatives}$$

in local Snell coordinates

$$\mathbf{K}^E(\mathbf{x}, \mathbf{r}, \mathbf{s}) \approx \underline{\mathbf{v}}_R^{(0)T} \frac{\partial \underline{\mathbf{t}}_{Sn}^{(0)}}{\partial n} - \underline{\mathbf{t}}_{Rn}^{(0)T} \frac{\partial \underline{\mathbf{v}}_S^{(0)}}{\partial n} \quad + \text{transverse terms}$$

Generalized Born v. 1D Bremmer

$$\begin{pmatrix} \mathbf{v} \\ -\mathbf{t}_j \end{pmatrix}_R^{(0)} = \mathcal{F}(\mathbf{x}, \mathbf{r}) \begin{pmatrix} \mathbf{g} \\ \mathbf{t}_j \end{pmatrix}(\mathbf{x}) \mathbf{g}^T(\mathbf{r}) \quad \text{ray amplitude coefficients}$$

\mathbf{g}, \mathbf{t}_j normalized for energy-flux along ray

$$\begin{pmatrix} \mathbf{v} \\ -\mathbf{t}_n \end{pmatrix}_R^{(0)} = \tilde{\mathcal{F}}(\mathbf{x}, \mathbf{r}) \begin{pmatrix} \tilde{\mathbf{g}} \\ \tilde{\mathbf{t}}_n \end{pmatrix}(\mathbf{x}) \mathbf{g}^T(\mathbf{r})$$

$\tilde{\mathbf{g}} = \left(\hat{\mathbf{n}} \cdot \hat{\mathbf{V}}_R \right)^{-1/2} \mathbf{g}$ normalized for energy-flux in $\hat{\mathbf{n}}$ direction

$$\tilde{\mathcal{F}} = \mathcal{F} \left(\hat{\mathbf{n}} \cdot \hat{\mathbf{V}}_R \right)^{1/2}$$

Generalized Born v. 1D Bremmer

$$\mathbf{K}^E(\mathbf{x}, \mathbf{r}, \mathbf{s}) \approx \underline{\mathbf{v}}_R^{(0)T} \frac{\partial \underline{\mathbf{t}}_{-S n}^{(0)}}{\partial n} - \underline{\mathbf{t}}_{-R n}^{(0)T} \frac{\partial \underline{\mathbf{v}}_S^{(0)}}{\partial n} \quad + \text{transverse terms}$$

$$\approx -\mathbf{g}(\mathbf{r}) \tilde{\mathcal{F}}_R \gamma \tilde{\mathcal{F}}_S \mathbf{g}^T(\mathbf{s}) \quad + \text{source/receiver directivity derivatives}$$

+ transverse terms
+ derivatives of $\tilde{\mathcal{F}}$

where

$$\gamma = - \begin{pmatrix} \tilde{\mathbf{t}}_{R n}^T & \tilde{\mathbf{v}}_R^T \end{pmatrix} \frac{\partial}{\partial n} \begin{pmatrix} \tilde{\mathbf{v}}_S \\ \tilde{\mathbf{t}}_{S n} \end{pmatrix} \quad \text{generalized Born}$$

$$= - \mathbf{W}_R^{\text{symplectic}} \mathbf{W}'_S \quad \text{1D Bremmer}$$

Conclusions – Perturbation Born

- standard perturbation Born provides the **Fréchet differential kernel**
- standard perturbation Born scattering theory is suitable for **small, isolated perturbations**
- it describes the travel-time differential kernel, which is **zero on the ray path**

Conclusions – Error Born

- generalized error Born scattering theory is needed for **extended scatterers**
- generalized Born models **reflections from gradients** as in the 1D Bremmer method
- forms foundation for inverse theory *a la* **1D exact inverse** methods
 - invert for **parameter gradients**
 - proceed as generalized Radon transform inversion except inverting for parameter gradients not parameters, with *curl-free* constraint
(R. Burridge, M.V. de Hoop, D. Miller and C. Spencer, 1998. Multiparameter inversion in anisotropic media, *Geophys. J. Int.*, **134**, 757-777)